

## defining semantics for complex systems part 3: iTask semantics

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## iTasks are wonderful



- **workflow management systems** supports and guides (administrative) tasks of humans and computers
  - entering data, approving transactions, ..
- the iTasks system is a combinator library to
  - specify workflows
  - execute tasks using a multi user web-interface
- **distinguishing features of the iTask system**
  - data dependent tasks
  - dynamic task creation and adaptation
- **iTasks are in the Clean distribution**
  - require generics, dynamics, iData and a little uniqueness

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## primitive tasks

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- **return** e.g. `return 1`
  - returns the given value
- **editTask** e.g. `editTask "ok" 7`
  - allows to edit a value until you press the button
- **buttonTask** e.g. `buttonTask "ok" (return 5)`
  - actually for every task `t`:  
`buttonTask s t = editTask s Void >>= \_ -> t`

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## compose task: choose a task

```
task1 :: Task Int
```

```
task1 = buttonTask "default" (return 1)
```

```
-||- editTask "done" 42
```

- iTask-systems generates a web-interface for task
  - `-||-` is or-operator for tasks
  - task is finished if **either**
    - the user presses the default button, **or**
    - presses the done button in the editor
- ```
(-||-) infixr 3 :: (Task a) (Task a) -> Task a
```

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## compose task: tasks in parallel

```
task2 :: Task (String, Int)
```

```
task2 = editTask "string" "u" -&&- editTask "int" 2
```

- -&&- is the and-operator
  - task2 is finished if **both**
    - the user presses the string button, **and**
    - presses the int button
- (-&&-) infixr 4 :: (Task a) (Task b) -> Task (a, b)

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## compose task: sequence of tasks

```
task3 :: Real -> Task Real
```

```
task3 x
```

```
= [ Text (toString x +
  " Forint = " +
  toString (x * exchange_rate) + " euro"), BrTag [] ]
```

```
?>> editTask "compute" x
```

```
>>= task3
```

a recursive task

- >>= is the monadic bind-operator
    - first do the task on the left, if that is finished
    - function on the right *generates* the next task
- (>>=) infixl 1 :: (Task a) (a -> Task b) -> Task b

data dependent

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## bind enables data dependency

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- the bind operator, >>=, gives the power to create data dependent tasks

```
task4 :: Task [Int]
```

```
task4
```

```
= [Text "number of bids?"]
```

```
?>> editTask "go" 2
```

```
>>= \n. if ( n < 1 || n > 10 )
```

```
  ([Text "between 1 and 10!"] ?>> task4)
```

```
  (andTasks [ ("bid", editTask "ok" 1)
```

```
    \ i <- [1..n]
```

```
  ])
```

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## some semantic questions about iTasks

```
task1 = buttonTask "default" (return 1)
```

```
-||- editTask "done" 42
```

- will the user be able to use the default button as soon as she starts editing the value 42?
- is the expression  $s -||- t$  equivalent to  $t -||- s$ ?
- is the expression  $s -\&\&- t$  equivalent to  $t -\&\&- s$ ?
- what is the value of  $\text{return } 0 -||- \text{return } 42$  ?

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## look at the definition of combinators

```

allTasksCond :: !String !(TasksToShow a) !(FinishPred a) ![LabeledTask a] -> Task [a] | iData a
allTasksCond label chooser pred taskCollection
= mkTask "andTasksCond" (doandTasks chooser taskCollection)
where
lengthTa
doandTa
doandTa
# ((alist,
| finished
| pred al
# select
# ((sele
# (_,tst
= (alist,
where
show
show
# (a
# (a
= ((i
che
| cta
# (taskname,task) = taskCollection!ctasknr
# (a,tst=:{activated = adone,html=html}) = ..

```

**this is not the way to answer semantic questions**

and many more (generic) functions



## why are the combinators so complicated?

- the definition of combinators does not give a quick answer to questions about the semantics
- combinators have several *interdependent* duties
  - produce html-code for the web interface displaying the current state of the task for each worker
  - handle inputs from the web, update task expression
  - interface to files and databases
  - multi-user
  - client/server
  - ..
- due to the large number of related jobs it is inevitable that the combinators are complicated

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## a solution

- in order to answer the semantic questions we define an operational semantics for iTasks
- in addition we want:
  - understand the system we are developing
    - guide decisions in the design and development
  - explain the behaviour to other people
  - reason about iTasks
  - use it as specification in model-based testing of the implementation of the iTask system
    - this connects the semantics and the implementation

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## how to define such a semantics ?

- it is kind of standard to define such a semantics using Scott brackets or horizontal bars
- however, such a specification is
  - hard to get correct and consistent
  - hard to validate
  - not suited for model-based testing of the system
- we use a functional programming language as carrier for the specification
  - language implementation checks types
  - simulation to validate the semantics
  - model-based test of the semantics
  - suited for model-based testing of the real system

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## a semantics for iTasks

- in order to reason about iTasks we define a simplified model of iTasks
  - based on a data type instead of functions
    - sequence operator contains function to guarantee enough expressive power (monadic bind)
  - some simplifications:
    - only basic iTask combinators
    - tasks can only handle a fixed number of types
  - concentrate first on event handling
    - ignore interface generation (HTML)
    - use a model of the world rather than real i/o

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## the data type for iTasks

the type iTask mimics Task a:

```

:: iTask
= EditTask    ID String BVal
| .|. infixr 3 ITask ITask
| .&&. infixr 4 ITask ITask
| >>- infixl 1 ID ITask (Val → ITask)
| Return     Val

:: Val    = Pair Val Val | BVal BVal
:: BVal   = String String | Int Int | VOID
  
```

edit only basic values

real function for sequences

a monad

```

ButtonTask id name task
:= EditTask id name VOID >>- λ x → task
  
```

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## advantages of a data structure for tasks

- in the semantics we can look at the structure of the task
- we can inspect the task to see what events are enabled
- we can even change the task if desired

### there is one exception

- in the bind operator we use a real function to maintain the expressive power

```

:: iTask = >>- infixl 1 ID ITask ( Val → ITask )
          | ..
  
```

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## one-to-one mapping from Task a to iTask

- we had the real iTask task

```

task1 :: Task Int
task1 = buttonTask "default" (return 1)
      -||- editTask "done" 42
  
```

- this is represented as

```

task1` :: iTask
task1` = ButtonTask "default" (Return (BVal (Int 1)))
      .|. EditTask "done" (Int 42)
  
```

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## events

- inputs for the task are called **events**
  - the iTask system and representation in its semantics both require events
    - we need to link events and tasks:
      - label the task and the event with a unique id
      - system should assign the id's
  - each event contains
    - ID: unique identification of subtask
    - the event kind: edit event with new value, or button event
- ```

:: ID          = ID [Num]
:: Event      = Event ID EventKind | ReFresh
:: EventKind  = EE BVal | BE
  
```

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## needed events

- needed events**: without these events the task cannot return a value
    - pressing the done button in an editor is needed
    - changing the value is not needed
- ```

colNeeded (EditTask id n v) = [Event id BE]
colNeeded (t1 .&&. t2) = colNeeded t1 ++ colNeeded t2
colNeeded (Bind id t f) = colNeeded t
colNeeded t              = [ ]
  
```
- in the semantic representation of task we can scan the data structure to find needed events
    - the function after a bind can generate needed events
    - the needed events of the generated task often depend on the result of the first task

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## the semantics

- semantics is specified by a function computing the new task given the current task and the event

```

(@.) infixl 9 :: ITask Event -> ITask
(@.) ( EditTask i n v ) ( Event j (EE w) ) edit event with new value
  | i == j = EditTask (next i) n w
(@.) ( EditTask i n e ) ( Event j BE ) button event
  | i == j = Return (BVal e)
(@.) ( t .||. u ) e
  = case t @. e of or combinator: first try left task
    t :: (Return _) = t
    t = case u @. e of
      u :: (Return _) = u
      u = t .||. u
  ..
  
```

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## iTask semantics part 2

```

..
(@.) ( t .&&. u ) e and combinator
  = case ( t @. e, u @. e ) of send event to both tasks
    (Return v, Return w) = Return (Pair v w)
    (t, u) = t .&&. u
(@.) ( Bind id t f ) e bind combinator
  = case t @. e of
    Return v = normalize id (f v)
    t = Bind id t f assign unique identifiers
(@.) t e = t
  
```

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## this answers our questions

- is the user able to press the button default after changing a value in the editor?

```
u = ButtonTask id1 "default" ( Return ( BVal ( Int 1 )))
  .|. EditTask id2 "done" ( Int 42 )
```

- equational reasoning

```
u @. Event id2 (EI 36)
```

```
→ ButtonTask id1 "default" (Return (BVal (Int 1)))
  .|. EditTask id2 "done" (Int 36)
```

- answer: user can still press the default button

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## equivalence of tasks

- there are various notions of equivalence for tasks

1. two tasks are equivalent if they yield the same result for any input sequence

- abstract from event Ids, they are invisible for users
- we can decide to look only at needed events

2. have exactly the same structure

3. ..

- we use the first notion of equivalence
  - task of different shape can be equivalent
- $$\text{EditTask } i \text{ s } 3 \approx \text{EditTask } i \text{ s } 3 \gg = \lambda v \rightarrow \text{Return } (id \ v)$$

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## equivalence relation

- simulation:  $s \subseteq t$ :

user can do anything with task  $t$  that can be done with  $s$

- ButtonTask id "ok" (Return 3)  $\subseteq$  EditTask id "ok" 3

- checking the shape of the tasks is not good enough

- in general we have to check if it responds identical to all input sequences

- equivalence:  $s \subseteq t \wedge t \subseteq s \Leftrightarrow s \approx t$

- we can approximate this property automatically

- using shape information can help to determine equivalence, but is in general not enough

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## equivalence of tasks

- given the tasks

```
s = editTask "a" 1
```

```
t = editTask "b" 2
```

- equivalence?

```
s -||- t ≈ t -||- s
```

- when are tasks equivalent  $x \approx y$  ?

- user can do the same with  $x$  and  $y$
- produce the same result for any sequence of events
- ignore differences in layout and event id's

- simulation  $x \subseteq y$  :

- user can do everything with  $y$  that can be done with  $x$

- $x \approx y \Leftrightarrow x \subseteq y \wedge y \subseteq x$

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### equivalence of tasks 2

- given the tasks  
 $s = \text{editTask "a" } 1$   
 $t = \text{editTask "b" } 5$
- equivalence  $s \dashv\vdash t \approx t \dashv\vdash s$  ?  
 > yes
- simulation  $s \dashv\vdash t \subseteq t \dashv\vdash s$ ,  
 $s \dashv\vdash t \subseteq t \dashv\vdash s$  ?  
 > yes

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### equivalence of tasks 3

- given the tasks  
 $s = \text{editTask "a" } 1$   
 $t = \text{editTask "b" } 5$
- equivalence  $s \approx t$  ?  
 > no, BE
- simulation  $s \subseteq t$ ,  
 $t \subseteq s$  ?  
 > no, idem

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### equivalence of tasks 4

- given the tasks  
 $s = \text{editTask "a" } 1$   
 $t = \text{buttonTask "b" (return 1)}$
- equivalence  $s \approx t$  ?  
 > no: EE 7, BE
- simulation  $s \subseteq t$  ?  
 > no: EE 7, BE
- simulation  $t \subseteq s$  ?  
 > yes: t only allows BE
- $s \approx t \Leftrightarrow s \subseteq t \wedge t \subseteq s$  ?

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### equivalence of tasks 5

- given the tasks  
 $t = \text{editTask "a" } 1$
- equivalence  $t \approx t \dashv\vdash t$  ?  
 > no: EE 7, BE
- simulation  $t \subseteq t \dashv\vdash t$  ?  
 > yes: use only 1 of the tasks in  $t \dashv\vdash t$
- simulation  $t \dashv\vdash t \subseteq t$  ?  
 > no: EE 7, BE
- be believed for a long time that  $t \approx t \dashv\vdash t$  !  
 > testing the semantics showed that we were wrong

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### equivalence of tasks 6

- given the tasks
  - s = editTask "a" 1
  - t = editTask "b" 1 >>= return
- equivalence  $s \approx t$  ?
  - yes, but shape of tasks is different
- simulation  $s \subseteq t, t \subseteq s$  ?
  - yes

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### equivalence of tasks 7

- given the tasks
  - s = editTask "a" 1
  - t = editTask "b" "Hi"
- equivalence  $s \text{-}\&\&\text{-} t \approx t \text{-}\&\&\text{-} s$  ?
  - no the types are different  
Task (Int, String) and Task(String, Int)
- simulation  $s \text{-}\&\&\text{-} t \subseteq t \text{-}\&\&\text{-} s, s \text{-}\&\&\text{-} t \subseteq t \text{-}\&\&\text{-} s$  ?
  - no, idem

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### equivalence of tasks 8

- given the tasks
  - s = editTask "a" 1 >>= f
  - t = editTask "b" 1 >>= g
- equivalence  $s \approx t$  ?
  - depends on the functions f and g
  - in general this is not decidable
  - we can approximate it by supplying sequences of events (like testing)
- simulation  $s \subseteq t, t \subseteq s$  ?
  - idem

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### approximation of equivalence

- if tasks are both of the form return v  
compare the values
- compare the needed events and the enabled events of tasks s and t, these should be equal
- apply different sequences of events and try again
- possible results:
  - Proof equal for all possible sequences of events,
  - Pass equal the used sequences of events,
  - CounterExample we found a difference,
  - Undefined no results found, e.g. infinite tasks

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## semantic properties

- what we want:
  - $\forall s t . (s . || . t) \approx (t . || . s)$
  - $\forall s t . (s . || . t) . || . u \approx s . || . (t . || . u)$
- some consequences:
  - task remain equivalent after applying a needed event  
 $s \approx t \Rightarrow \forall i \in \text{neededEvents } s . s @ . i \approx t @ . i$
  - $\forall i \in \text{neededEvents } u . u @ . i \approx (t . || . s) @ . i$   
 where  $u = s . || . t$
  - we can apply needed events in any order  
 $\text{is} = \text{neededEvents } t . t @ . i \approx t @ . \text{permutation is}$

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## checking the system

- having defined reduction and equivalence there are interesting questions
  - do the required properties hold
  - is the system consistent
  - ..
- checking this manually is tedious and error prone
- a proof system requires a significant amount of human guidance
- use our test system  $G \forall st !!$ 
  - express the properties using the logical combinators
  - generation of test data is done by the generic system, a little guidance by an additional data type is necessary

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## testing a property

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- what we want:
  - $\forall s t . (s . || . t) \approx (t . || . s)$
- in *Gast*:
  - $\forall st.$
  - `pOr1 :: ITask ITask -> Property`
  - `pOr1 s t = (s . || . t) ~ ~ (t . || . s)`
- the test result
  - "pOr1" Counterexample 1 found after 23 tests:  
 (Return (BVal (Int 0)))  
 (Return (Pair (BVal (Int 0)) (BVal (Int 0))))
- a correct property
  - $\forall s t . \neg \text{NF } s \wedge \neg \text{NF } t \Rightarrow (s . || . t) \approx (t . || . s)$
  - `pOr s t = notNF [t, u] ==> (s . || . t) ~ ~ (t . || . s)`

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## examples of automatic testing

- first test our property of the or-operator:
  - `pOr :: ITask ITask -> Property`
  - `pOr s t = notNF [t, u] ==> (s . || . t) ~ ~ (t . || . s)`
  - Start = test pOr  $\forall st.$
- test execution yields: Passed after 1000 tests
- `pAnd s t = (s .&&. t) ~ ~ (t .&&. s)`
  - Counterexample: (GButtonT "b" (GReturn (BVal (Int 0))))  
 (GReturn (BVal (String "a")))
- the types of the subtasks are different !

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## automatic generation of tasks for tests

- systematic automatic generation of test cases is desired
  - easy to do more tests
  - we do not forget tasks
- the data type iTask also allows bad test tasks
  - nonterminating
  - badly typed
- use an additional data type for desired test tasks
  - generate instance by the generic algorithm
  - transform these tasks to proper test tasks
  - very similar as we did for terminating While-programs

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## how to obtain properties

- 'obvious' properties arise during the development of the semantics
  - associativity of  $-||-$ , ..
- learn from your semantical mistakes
  - turn each example of undesired behaviour into a test
  - try to generalize these mistakes to general properties
  - $(s .||. t) \approx (t .||. s)$  only holds iff  $s$  and  $t$  are can consume events
- learn from your test results
  - turn each counterexample into a test (is it still correct)
  - try to generalize these errors to general properties

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## validating the semantics

- semantics with properties can be consistent, but wrong
  - testing does not reveal all problems
- validation by simulating and human inspection
  - since our tasks are data structures we can edit them with a standard iTask for this data type!
  - we can simulate the task using the executable semantics

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## a screen shot of the simulator

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## a methodology for defining consistent semantics

- semantics is a formal artefact (like a program)
  - we need tool support to get it correct
- use a functional programming language as carrier of the semantics
  - Haskell, Clean, Erlang, F#, ..
  - compiler spots mistakes with types and identifiers
- simulate the semantics to validate it using iTasks
- use model-based testing for regression tests: *Gast*
  - learn from your mistakes
- [optional] prove the tested properties
  - proving is much more work than model-based testing

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## conclusions

- the iTask system needs a semantics
  - we need to know what we are building
  - explain the system
  - model-based test of the implementation
- we defined an operation semantics and equivalence
- a functional programming language is very suited to construct such a semantics
  - concise
  - compiler checks types
  - automatic testing of desired properties of the semantics
    - we have results in seconds
  - validation by simulation
  - edit tasks in the simulator

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## future work

- extend the semantics to cover:
  - multi-user tasks
  - access to databases and files
  - exceptions
  - dynamic changes of the running tasks
  - ..
- test if the real iTask system behaves as specified
- prove properties that are tested successfully

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## the end

- Thanks for your attention
- questions ??



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