## **Mechanics**

## Ildikó László, PhD



Dept. Programming Languages and Compilers Eötvös Loránd University, Budapest, Hungary

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Kinematics - Motion in one Direction

#### Dinamics

 - in our everyday life we are surrounded by different objects, like houses, mountaines and so on..

- there are also much bigger objects around us, like the Moon the Sun or stars and galaxies, which form the macrocosmos;
- but there are also atoms, electrons or bacteria which form the microcosmos;
- there is a very big difference between the dimensions of these objects or systems;
- in order to deal with them we are using units;

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- it is important, to be aware of that, that the measurement of any quantity is made relative to a particular standard or unit, which has to be specified;
- one cannot say, that the weight of a child is 57;
- 57 kg., or 57 pounds? has to be specified;
- until about 200 years ago, the units of measurement were not standardized, and different nations used different units;
- there is still a difference in the units used especially in Europe, and that used in England or USA;

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- it was said, that one of the reasons for the explosion of a spacecraft was caused by mixing up these two different units;
- British units of length, *inch, foot, mile,* are defined in SI units, which comes from the French word Systeme International;
- Sl units

quantityunitabbrev.LengthmetermTimesecondsMasskilogramkgTemperaturekelvinKEl. currentampereA

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## - SI units

quantity	u	nit	abb	rev.
Length	m	eter	m	
Time	se	econd	S	
Mass	kil	ogran	n k	g
Temperatu	ire	ke	lvin	Κ
El. current	t	amp	ere	Α

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## Important metric (SI) prefixes and multipliers

• -	SI unit	ts		
	Prefix	Ab	brev.	Value
	Tera	Т	10 <sup>12</sup>	
	Giga	C	G 10 <sup>9</sup>	)
	Mega	ľ	M 10 <sup>6</sup>	
	Kilo	k	10 <sup>3</sup>	
	Hecto	h	10 <sup>2</sup>	
	Deka	da	10 <sup>1</sup>	
	Deci	d	10 <sup>-1</sup>	
	Centi	С	10 <sup>-2</sup>	
	Mili	m	10 <sup>-3</sup>	
	Nano	n	10 <sup>-9</sup>	
	Pico	р	10 <sup>-12</sup>	
	Femto	f	10 <sup>-15</sup>	

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- Kinematics is that part of mechanics, which gives the description of how objects move;
- although motion has been studied from ancient ages the modern understanding of motion was established only in the sixteenth and seventeenth centuries;
- the most famous of those, who contributed to this were
- ▶ Galileo Galilei (1564 1642) and
- Isaac Newton (1642 1727);

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- the motion of rigid objects that move without rotating is called *translational motion;*
- in order to establish those laws which describe such translational motion, we use the concept of an idealized particle;
- such an idealized particle is considered to be a mathematical point, with no spatial extent;

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- it is important to emphasize, that every measurement can be made with respect to a frame of reference;
- that is, it is always important to specify the system of reference when you are stating the value of a physical quantity;
- for ex. a person passing by you in a train:
  - has different speed with respect to you, who are sitting there,
  - or in respect to a person standing on the ground, or
  - sitting in another train passing by in oposite direction and so on;

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- the study of the motion of objects together with the related concepts like force and so on, is called mechanics;
- rigid objects that move without rotation, are sad to undergo translational motion;
- we will start with translational motion;

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## we will use the terms speed and velocity as well;

- what each of them means?
- speed is used to express the magnitude of how fast an object is moving; it is a scalar quantity,
- velocity expresses not only the magnitude, but also the direction of the motion as well;
- velocity it is a vector;

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- displacement is defined as the change in position of the object;
- a person is walking through a path s in a forest from point a. to point b.;
- his displacement is only that given by the deshed arrow;



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for simplicity lets consider a rectilinear trajectory;



- at an initial time t<sub>1</sub> an object starts from point x<sub>1</sub> and arrives at x<sub>2</sub> in moment t<sub>2</sub>, then
- the average velocity defined as the the displacement divided by the elapsed time is:

$$\bar{v} = \frac{x_2 - x_1}{t_2 - t_1};\tag{1}$$

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 the instantaneous velocity is the average velocity taken in the limit of an infinitesimally small time interval;

$$\vec{v} = \lim_{\Delta t \to 0} \frac{\vec{\Delta x}}{\Delta t} = \frac{\vec{dx}}{dt};$$

 this is the instantaneous velocity for one-dimensional motion;

- generally:

$$\vec{v} = \lim_{\Delta t \to 0} \frac{\Delta \vec{r}}{\Delta t} = \frac{d\vec{r}}{dt};$$

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- when the magnitude of the acceleration is constant and the motion is rectilinear, the acceleration can be given by:

$$a=rac{v_2-v_1}{t_2-t_1};$$

▶ - let us consider the initial time 
$$t_1 = 0$$
,  $x_1 = x_0$  and denote  $t_2$  by  $t$  and  $x_2 = x$ ;

then the average velocity is:

$$\bar{v} = \frac{x - x_0}{t};\tag{5}$$

- and the acceleration is:

$$a = \frac{V - V_0}{t};\tag{6}$$

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 the position of an object in a uniformly accelerated motion can be expressed like:

$$x = x_0 + \overline{v}t;$$

- where the average velocity is given by:

$$\bar{v}=\frac{v+v_0}{2};$$

- from where we get:

$$x = x_0 + v_0 t + \frac{1}{2}at^2;$$
 (9)

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 the position of an object in a uniformly accelerated motion can be expressed like:

$$x = x_0 + \bar{v}t;$$

• where the average velocity is given by:

$$ar{v}=rac{v+v_0}{2};$$

- from where we get:

$$x = x_0 + v_0 t + \frac{1}{2}at^2; (9)$$

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$$\bar{\nu}=\frac{\nu+\nu_0}{2}; \tag{8}$$

- from where we get:

$$x = x_0 + v_0 t + \frac{1}{2} a t^2; \qquad (9)$$

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- we discussed uniform and uniformly accelerated motion without asking, what causes an object at rest, let's say, to start to move;
- it is said, that Aristotle (a.C.384 a.C.322) believed that a force was required to keep an object moving along a horizontal plane;
- after almost 2000 years later Galileo Galilei (1564 – 1642) was able to imagine an idealized case, where there is no friction;
- this let him to conclude, that it is just as natural for an object to be at rest as it is to be in a horizontal motion;

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#### Dinamics - Newton's Laws

- Galileo finally came to the conclusion that an object will continue moving with constant velocity if no force acts on it;
- based on this foundation, Isaac Newton (1643 – 1727) summarized his famous laws of motion in his great work: **Principia**;
- Newton's First Law states that:
- an object will remain at rest or in uniform motion in a straight line unless acted upon by an external force;

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#### Dinamics - Newton's Laws

### • what happens, if a net force is acting on a body?

- Newton came to the result that as a result the velocity of the body will change;
- that is, the net force gives rise to acceleration;
- Newton's Second Law states that:
- the acceleration of an object is directly proportional to the net force acting on it and is inversly proportional to its mass;

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### - which can be expressed by a vector equation:

$$\vec{F} = m\vec{a};$$

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#### Dinamics - Newton's Laws

- a force applied to any object it is always applied by another object;
- Newton's Third Law states that:
- whenever an object exerts a force on another object, the second exerts an equal and opposite force on the first one; ;
- it is important to emphasize, that the action- and the reaction forces are acting on different objects;



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# The Force of Gravity

 as you could see at the discussion of Newton's third law at any object acts a force;

- Galileo came up with the idea that objects drop near the surface of the earth because the earth exerts a force on them;
- Galileo stated that their acceleration is the same g;
- the force exerted by the earth on the objects is called force of gravity;
- applying Newton's second law we have:

$$\vec{G} = m\vec{g}; \tag{11}$$

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### The Force of Gravity - Free fall

- if an object, near to the surface of the earth it is allowed to fall vertically, due to the gravitational force, this will be a uniformly accelerated motion;
- let us assume, that the object is falling from a hight h where its initial velocity is zero;
- its acceleration due to gravity will be g and its position and velocity at a certain moment t will be given by:

$$y = h - \frac{1}{2}gt^2$$
; and  $v = gt$ ; (12)



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Dinamics - Newton's Laws

- let's take an object of mass m on an incline, which makes an angle θ with the horizontal plane;
- - the earth exerts a force  $\vec{G}$  on it;
- ► the normal component of this force  $\vec{F_n}$  is acting on the incline; ( which exerts an equal and opposite force on the object of mass *m* not on the figure;)



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Dinamics - Newton's Laws

- - the magnitude of the normal component acting on the incline is  $F_n = mgcos\theta$  and the component paralell with the plane of the incline is  $F_t = mgsin\theta$ ;
- conform Newton's second law, the object, if no other force acts on it, will have a uniformly accelerated motion, with an acceleration given by

 $ma_t = mgsin\theta$ ; that is :  $a_t = gsin\theta$ ; (13)

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- whenever an object is placed on another object, or is moving on it, between them appears a friction;
- theis is caused by the roughness of the two surfaces;
- the friction which acts on an object sliding on another one, is called *kinetic friction*;
- the force of kinetic friction acts opposite to the direction of the object's motion;

$$F_{fr} = \mu_k F_n; \tag{14}$$

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 if an object is thrown horizontally with an initial velocity v<sub>0</sub>, from a height y<sub>0</sub> then

- the horizontal motion is a uniform motion;
- and the vertical motion is a uniformly accelerated motion, with an acceleration -g;



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### - the equations of the horizontal motion are:

$$v_y = gt;$$

$$y = y_0 - \frac{1}{2}gt^2;$$
 (16)

- and

$$x = v_0 t; \tag{17}$$

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Dinamics - Newton's Laws

- the equations of the horizontal motion are:

$$v_y = gt;$$

$$y = y_0 - \frac{1}{2}gt^2;$$
 (16)

- and

$$x = v_0 t; \tag{17}$$

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Dinamics - Newton's Laws

 - it is called projectile motion that motion of an object, which is projected into the air with an initial velocity
 v<sub>0</sub> under an angle α with the horizontal plane;



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Dinamics - Newton's Laws

### let the motion be in the xy plane as in the figure;

- then, the components of the acceleration are:

$$a_x = 0 \text{ and } a_y = -g; \tag{18}$$

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### - the components of the initial velocity $v_0$ will be:

$$v_{x0} = v_0 \cos \alpha$$
 and  $v_{y0} = v_0 \sin \alpha$ ; (19)

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Dinamics - Newton's Laws

- since a<sub>x</sub> = 0, the horizontal motion is a uniform motion with a constant speed v<sub>x0</sub>, that is:

 $x = v_{x0}t = v_0 t sin\alpha;$ 

► - in the vertical plane the object has an acceleration a<sub>y</sub> = -g that is, the motion is a uniformly accelerated motion:

$$y = v_{y0}t - \frac{1}{2}gt^2 = v_0 tsin\alpha - \frac{1}{2}gt^2;$$
 (21)

- and

$$v_0 = v_{y0} - gt = v_0 \sin\alpha - gt; \qquad (22)$$

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Dinamics - Newton's Laws

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Dinamics - Newton's Laws

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Dinamics - Newton's Laws

Dinamics - Applications of Newton's Laws

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## The de Broglie Hypothesis

- de Broglie suggested that
  - the electron wave must be a circular standing wave that closes in itself;
- - that is:  $2\pi r_n = n\lambda$

### - then, for an electron orbiting on a circle

- of radius *r<sub>n</sub>* this follows:

 $mvr_n = \frac{nn}{2\pi};$ 

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Dinamics - Newton's Laws

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Dinamics - Newton's Laws

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$$\frac{e}{m} = \frac{E}{rB^2};$$
(23)

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